

**Canadian Association of Road Safety Professional  
Conference 2017**

**EVALUATION OF LEVEL-OF-SERVICE AND SAFETY INDICATOR OF  
BICYCLE TRAFFIC LIGHT TREATMENTS AT SIGNALIZED INTERSECTIONS**

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Supervised by: Prof. Luis Fernando Miranda-Moreno

CO-HOSTED BY:



Ontario

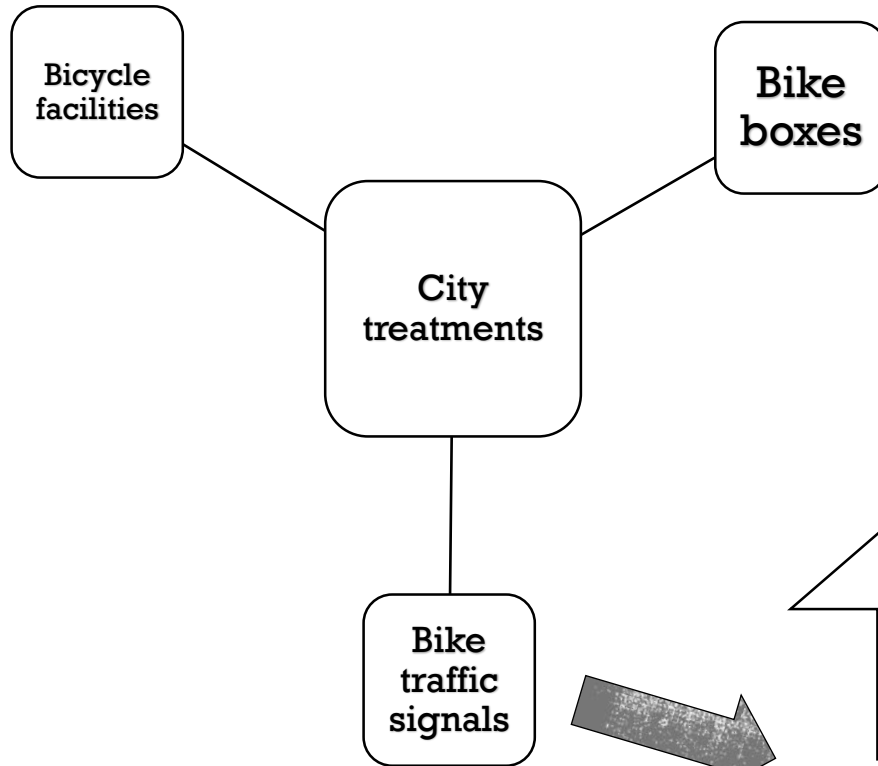


# INTRODUCTION

- In Montreal, the utilization of cycling infrastructure has increased significantly over the last 10 years.
  - Faster commuting option in urban areas
  - Avoid congestion
  - Reduction in emissions and noise pollution
  - Cheaper infrastructure
  - Public health improvement
- However, road safety for cyclists is still a major concern
  - Increase in bicycle ridership results in an increase in the number of dangerous interactions and collisions between motor vehicles and non-motorized modes



# INTRODUCTION



+ Reduction of vehicle-bike conflicts, red violations, and collisions

+ Increase in level of service by reducing bicycle delays.

- Increasing delays for motorized road users



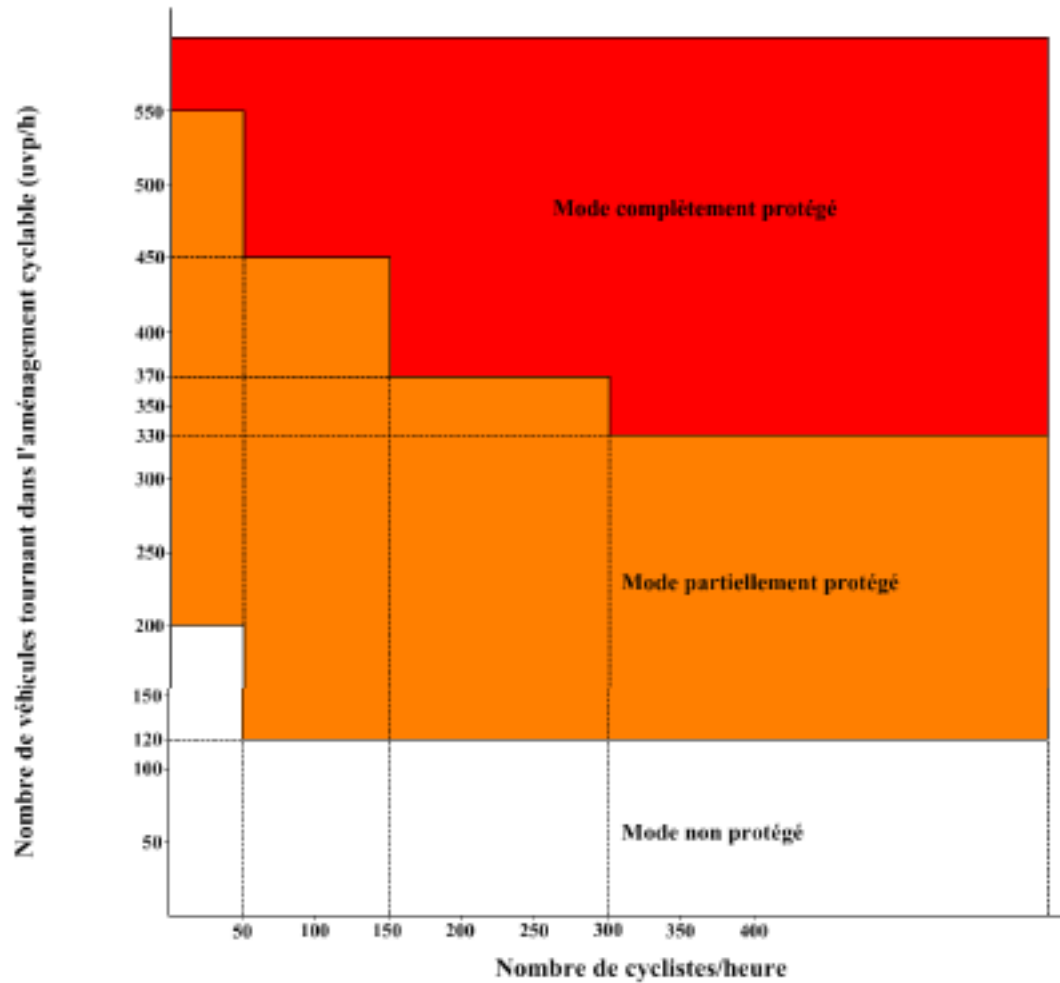
# INTRODUCTION

- Several key questions regarding the installation of bicycle signals must be addressed.
  - Criteria to identify the intersections that would benefit from treatment
  - Potential impacts of introducing bike signals and how can the impacts be measured?
- In an attempt to address the questions surrounding the implementation of bicycling signals, the Dep Transportation of the City of Montréal has unimportant step in the development of a bicycle guide



# CRITERIA - PROPOSED METHODOLOGY

Figure 2: Mode de fonctionnement recommandé en fonction du nombre de conflits véhicules/cyclistes

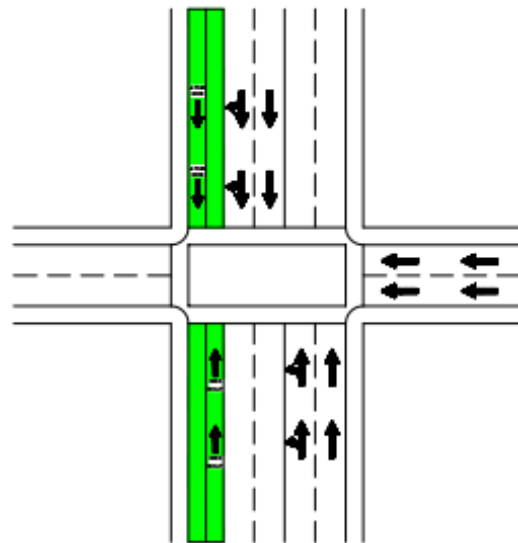


# STUDY OBJECTIVES

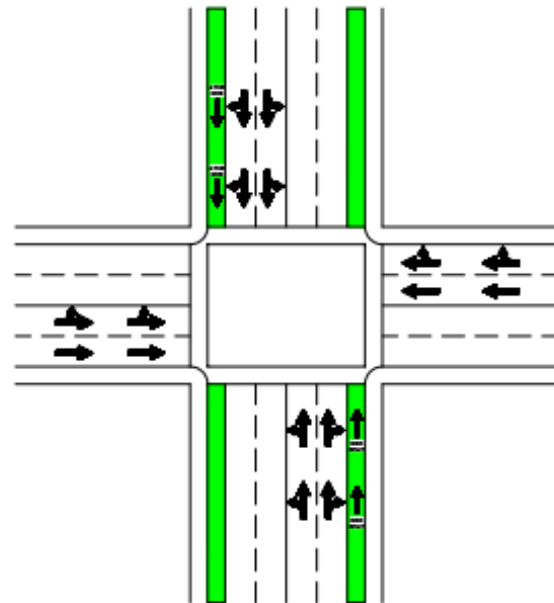
- Help evaluating the proposed guidelines for Montreal “Guide de conception des feux en présence d’aménagements cyclables »
- Investigate the impact of different signals strategies in terms of congestion and safety:
  - Non protected or Base case - BC
  - Partially protected - PP
  - Completely protected – CP
  - “Completely protected with protected turn” - CPT



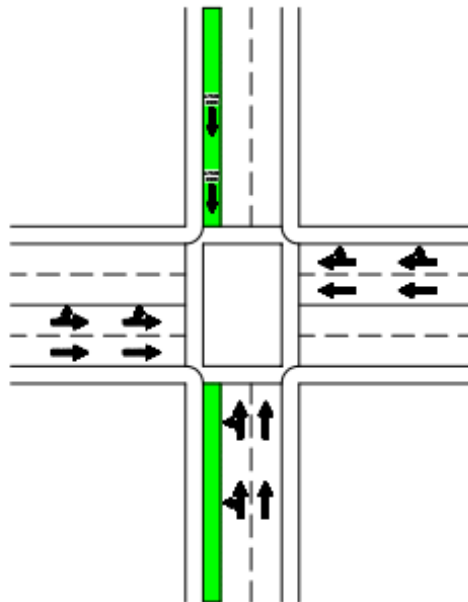
# MODEL INTERSECTIONS



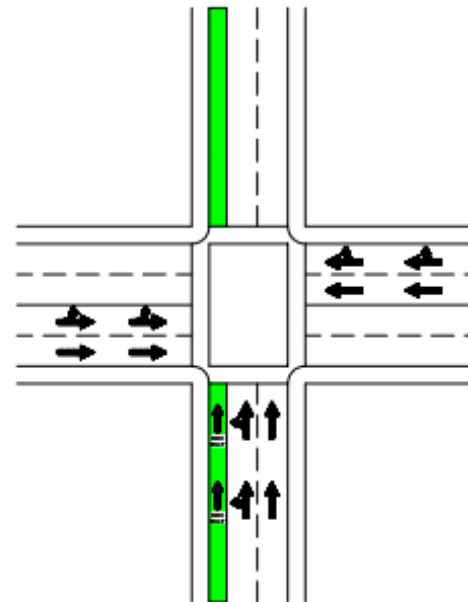
A. Left bike lanes



B. Bike lanes at both sides



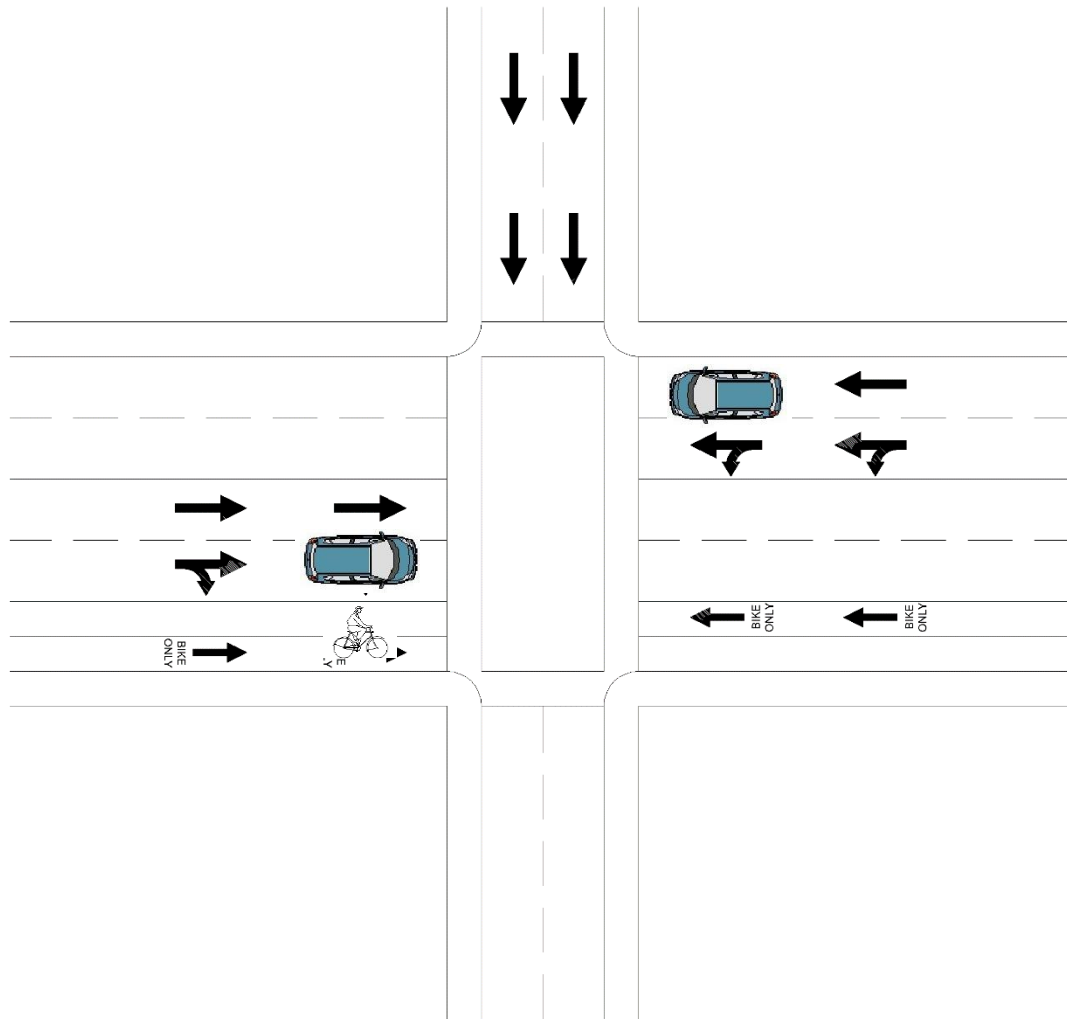
C. Contraflow bike lane



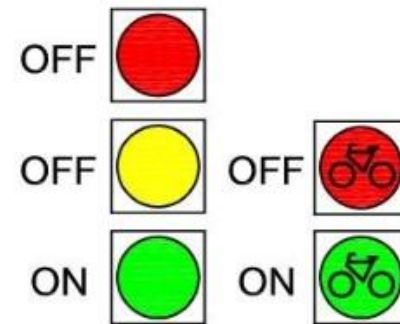
D. Left bike lane



# TRAFFIC PHASES, BASE CASE (BC)



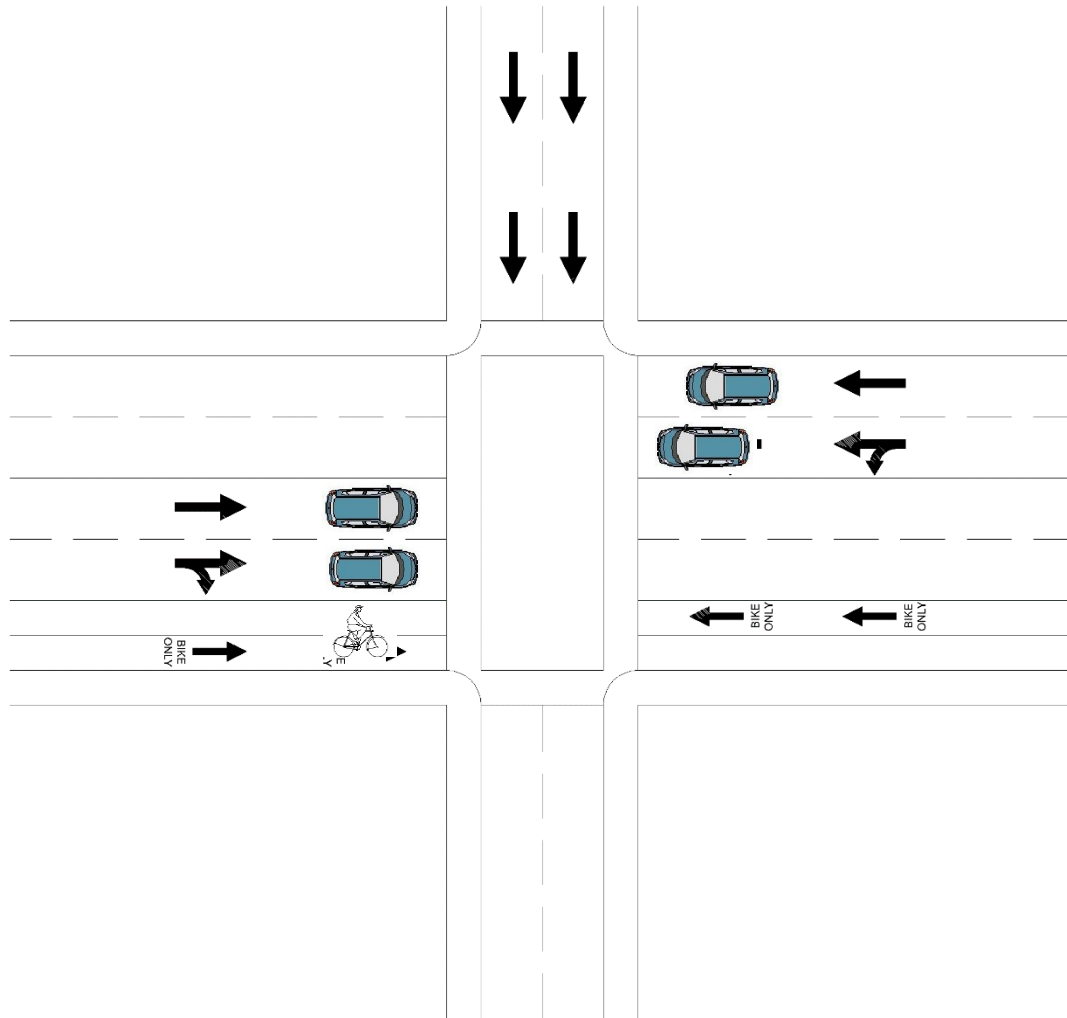
A, Base Case (BC). This is the traditional traffic light treatment where all users move simultaneously in the same phase



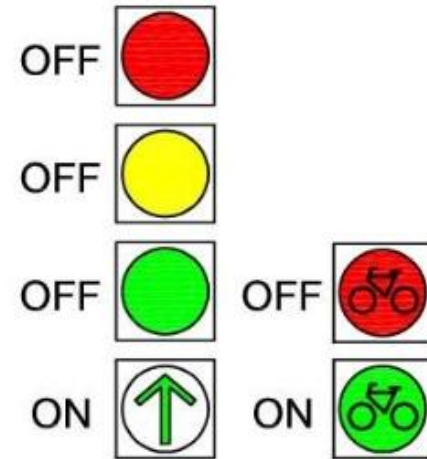
A. Non protected



# TRAFFIC PHASES, PARTIALLY PROTECTED (PP)



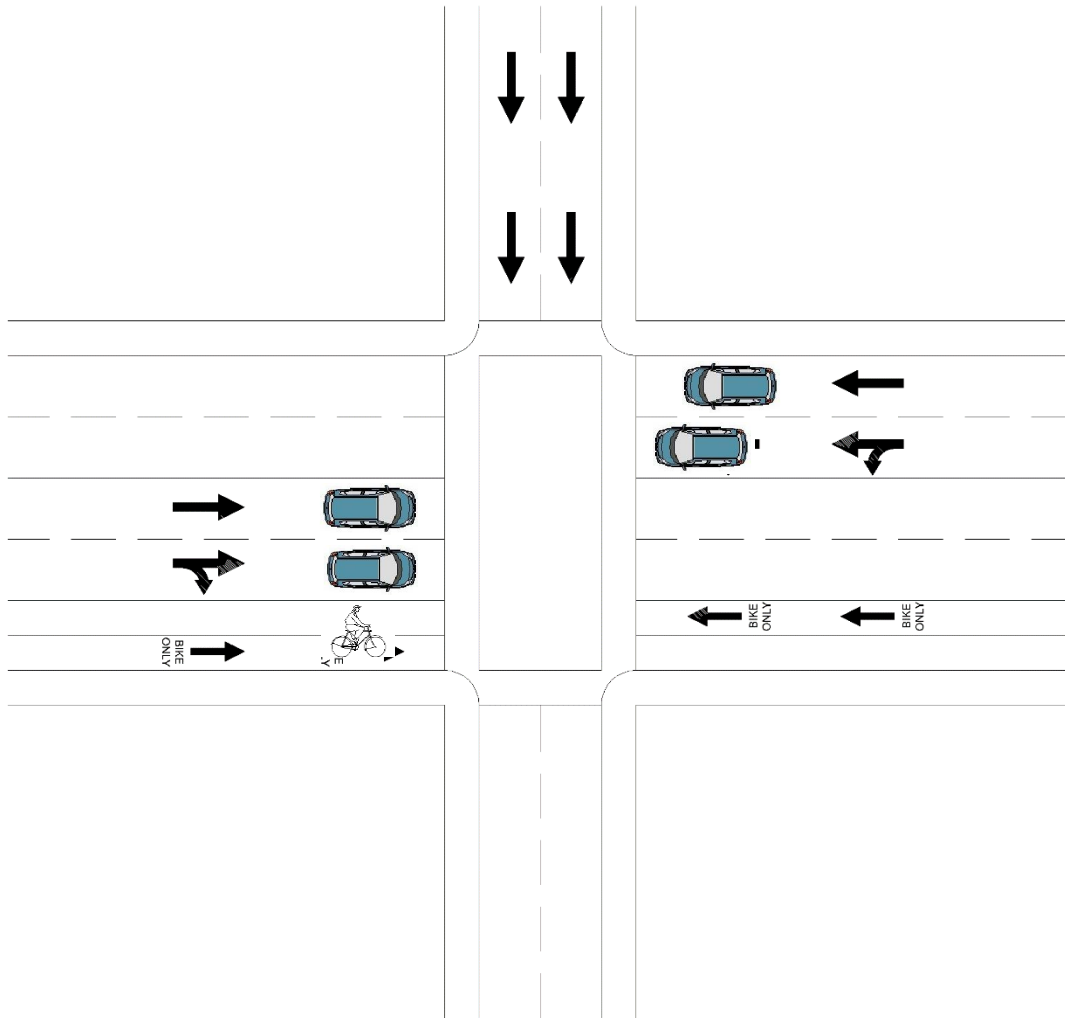
B, Partially Protected (PP).  
Cyclists or/and pedestrians have a leading green while through movements are allowed for vehicles.



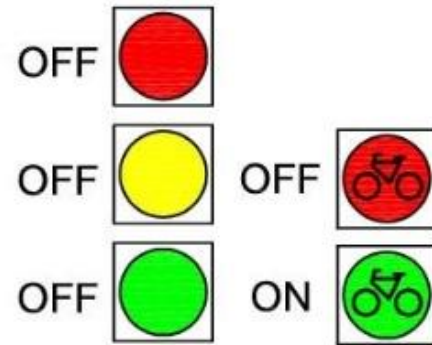
B. Partially protected



# TRAFFIC PHASES, COMPLETED PROTECTED (CP1)



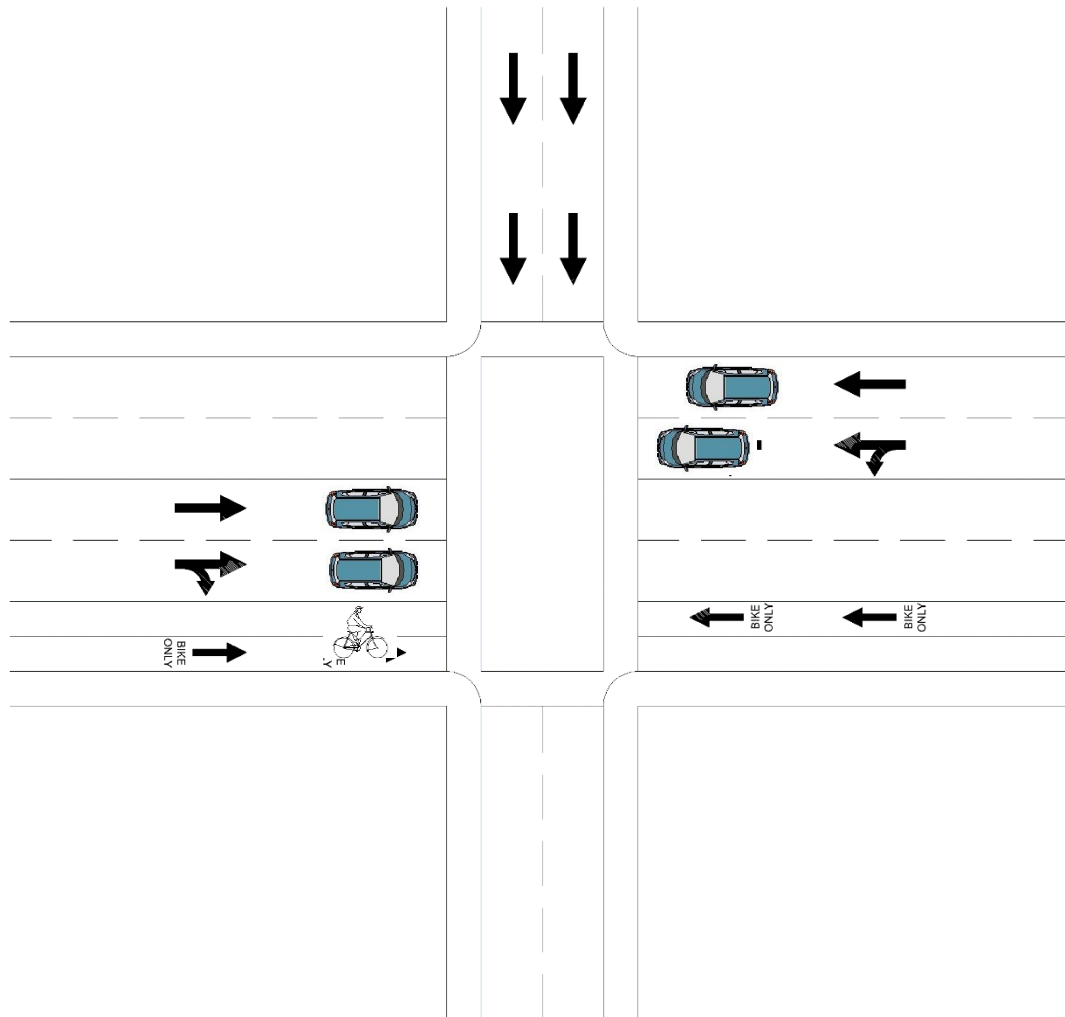
C, Completed Protected (CP1). This design gives the cyclists or/and pedestrians a leading green while all vehicle movement is restricted



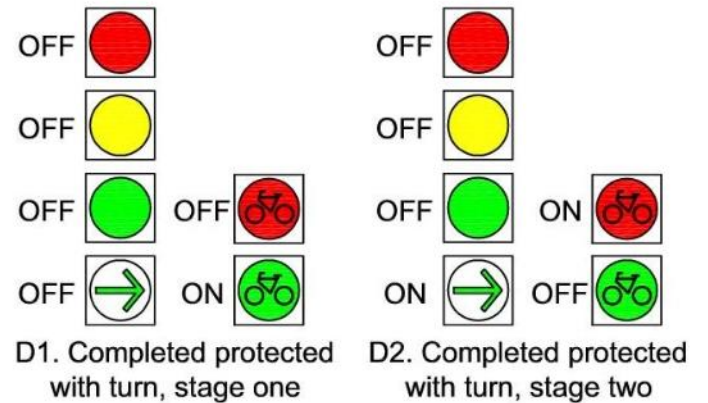
C. Completed protected



# TRAFFIC PHASES, COMPLETED PROTECTED 2 (CP2)



D, Completed Protected 2 (CP2), This mode is similar to C, but at the end of the green phase it stop cyclist and vehicles going through for some seconds allowing turning vehicles to do so without major conflicts.



# SIGNAL PHASES CYCLES (84S)

Direction	Intersection 1 and 2							
	Base Case							
Main (All)	47		3	2	30		2	
Secondary (All)	50			2	27	3	2	
	Partially Protected							
Main - Through (Veh)	10	37		3	2	30		2
Main - Turning (Veh)	10	37		3	2	30		2
Main (Bike)	10	37		3	2	30		2
Secondary (All)	50			2	27	3	2	



# TRAFFIC INPUTS

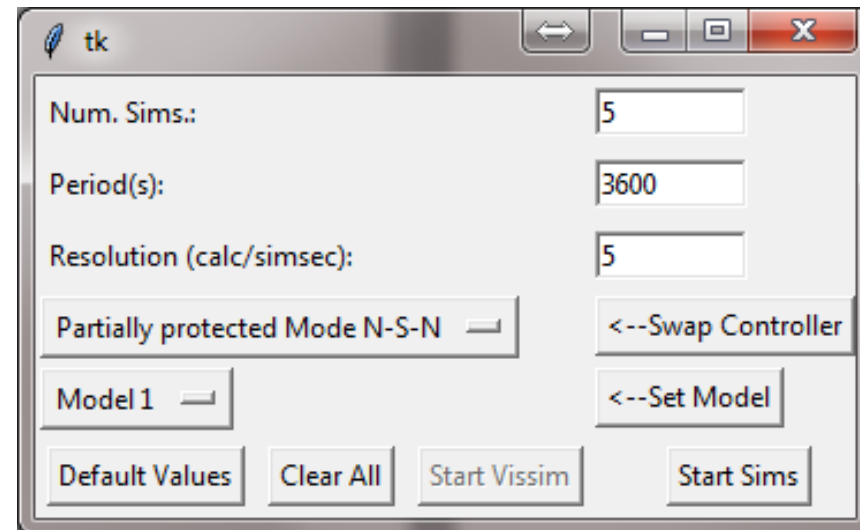
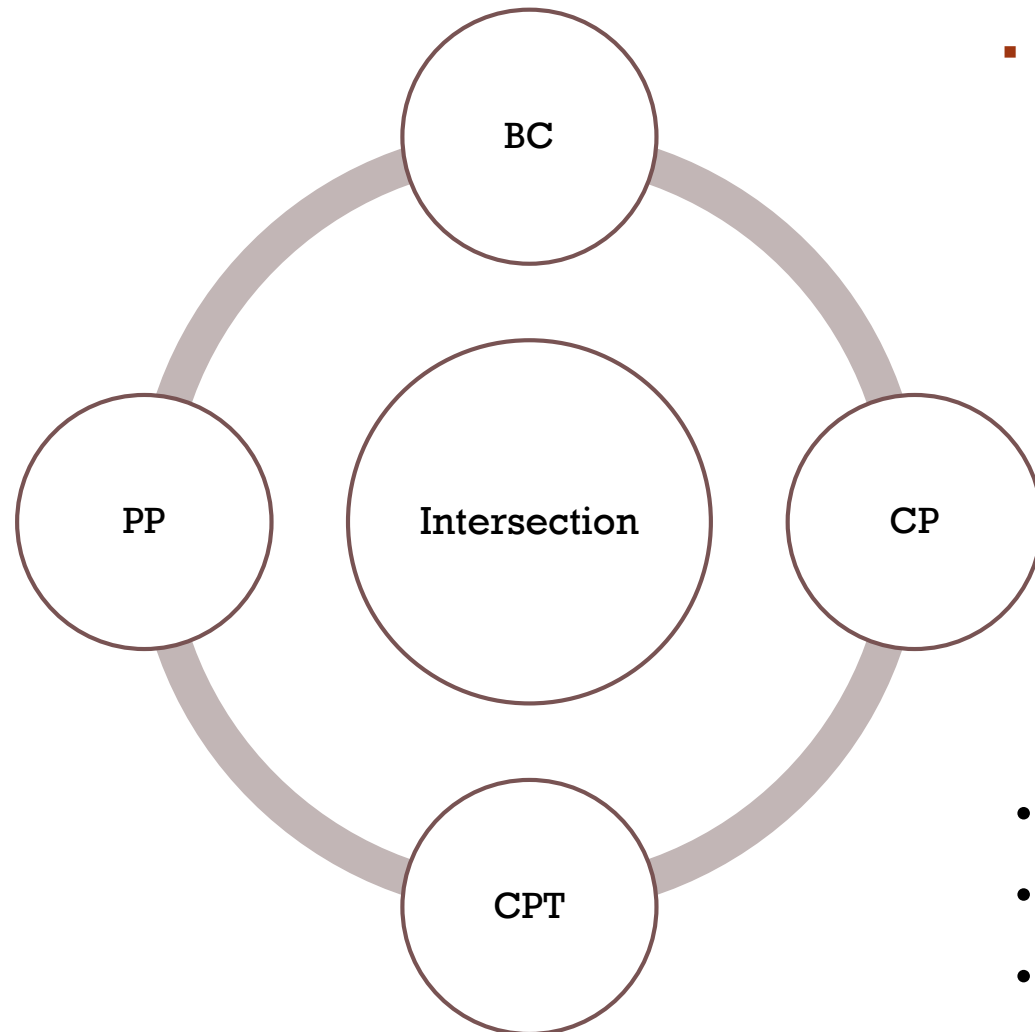
Vehicles	Cyclist												
	1	50	100	150	200	250	300	350	400	450	500	550	600
50													
100													
150													
200													
250													
300													
350													
400													
450													
500													
550													
600													

- Vehicles speed, 50 km/h.
- Cyclists speed, 80% at 15 km/h, and 20% at 20 km/h.



# SIMULATION, VISSIM V5.4

- 4 different intersections
- 156 different traffic flow combinations
- 624 simulation sets per intersection

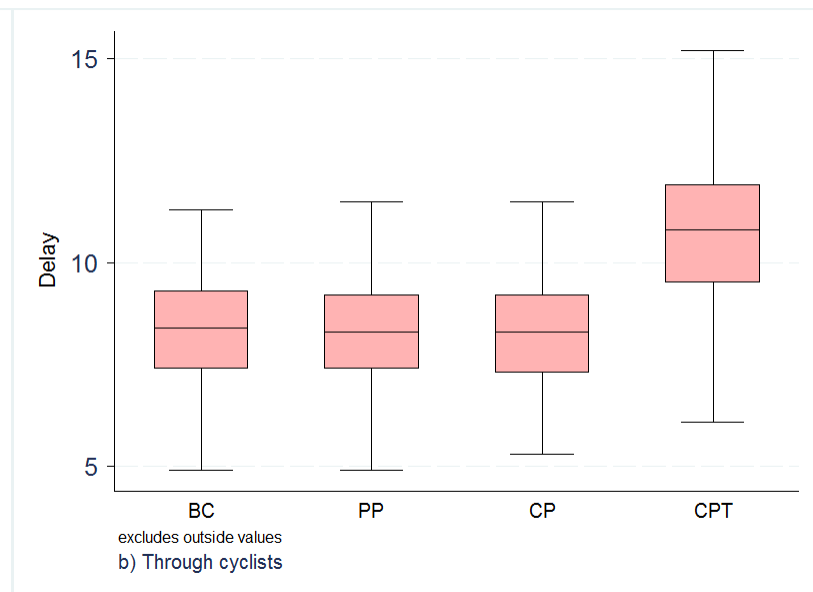
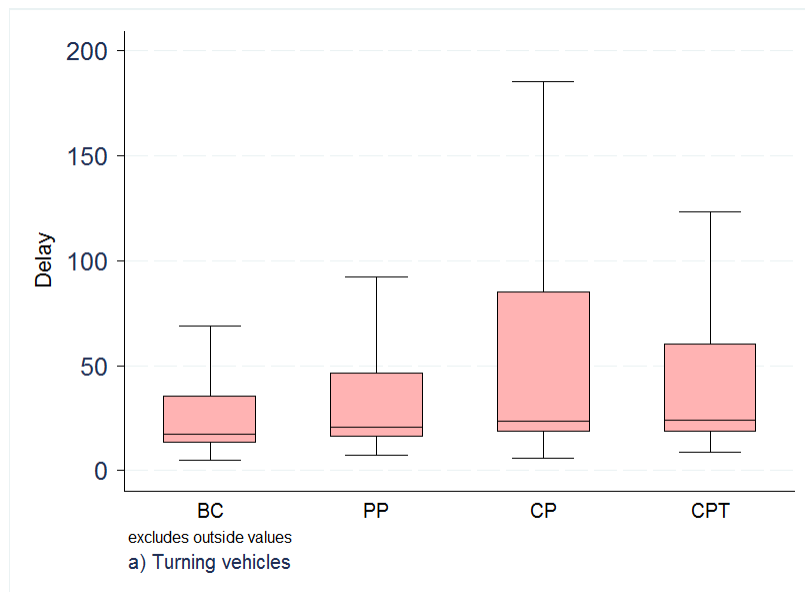


- 2,496 simulations sets
- 10 unique simulations per set
- 24,960 total simulations

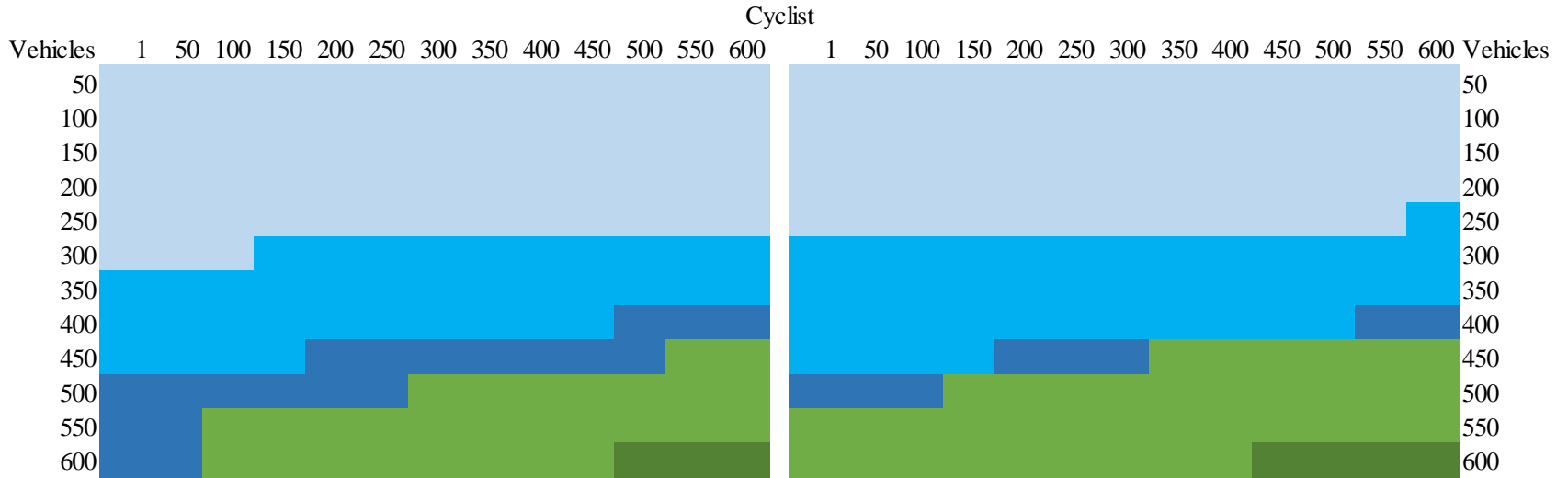


# RESULTS, INTERSECTION 1 SUMMARY

Variable	Light phase			
	BC	PP	CP	CPT
Through vehicles median (s)	10.6	10.8	16.7	20.0
Through vehicles IQR (s)	3.6	4.8	8.45	9.75
Turning vehicles median (s)	17.5	20.6	23.6	23.9
Turning vehicles IQR (s)	22.35	30.5	66.95	41.95
Through cyclists median (s)	8.4	8.3	8.3	10.8
Through cyclists IQR (s)	1.9	1.8	1.9	2.4
Crossing conflicts	678	390	293	402



# INTERSECTION 1, LOS THROUGH VEHICLES



a) BC average delay time for through vehicles

b) PP average delay time for through vehicles



c) CP average delay time for through vehicles

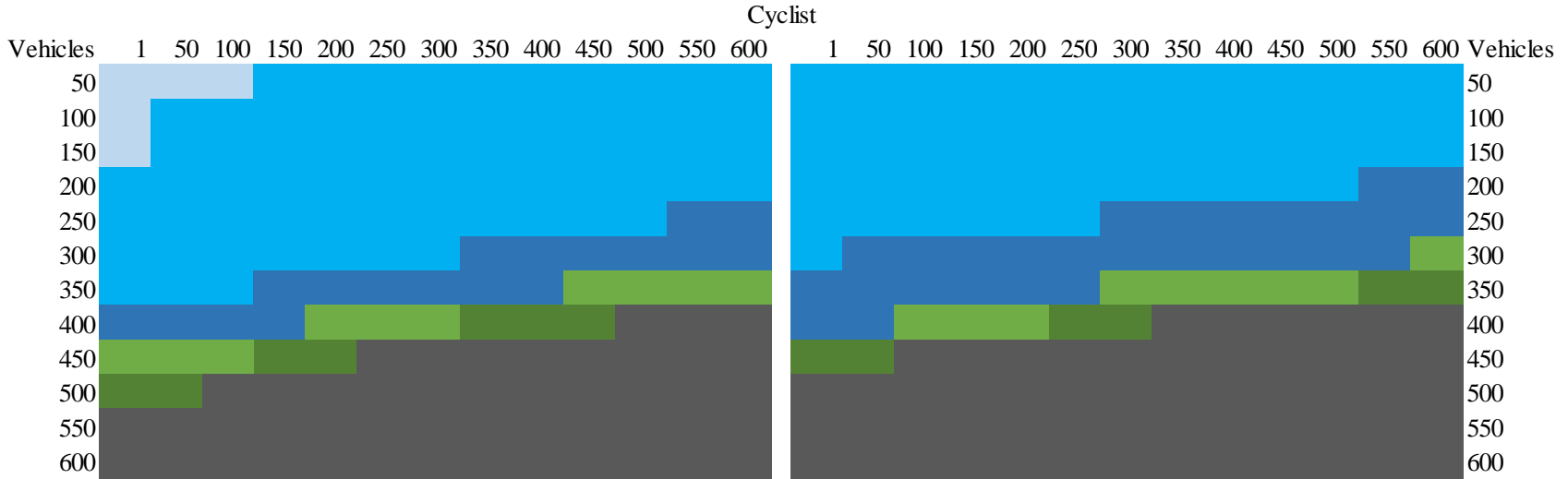


d) CPT average delay time for through vehicles

LOS Definition      A   < 10    B   10 - 20    C   20 - 35    D   35 - 55    E   55 - 80    F   > 80

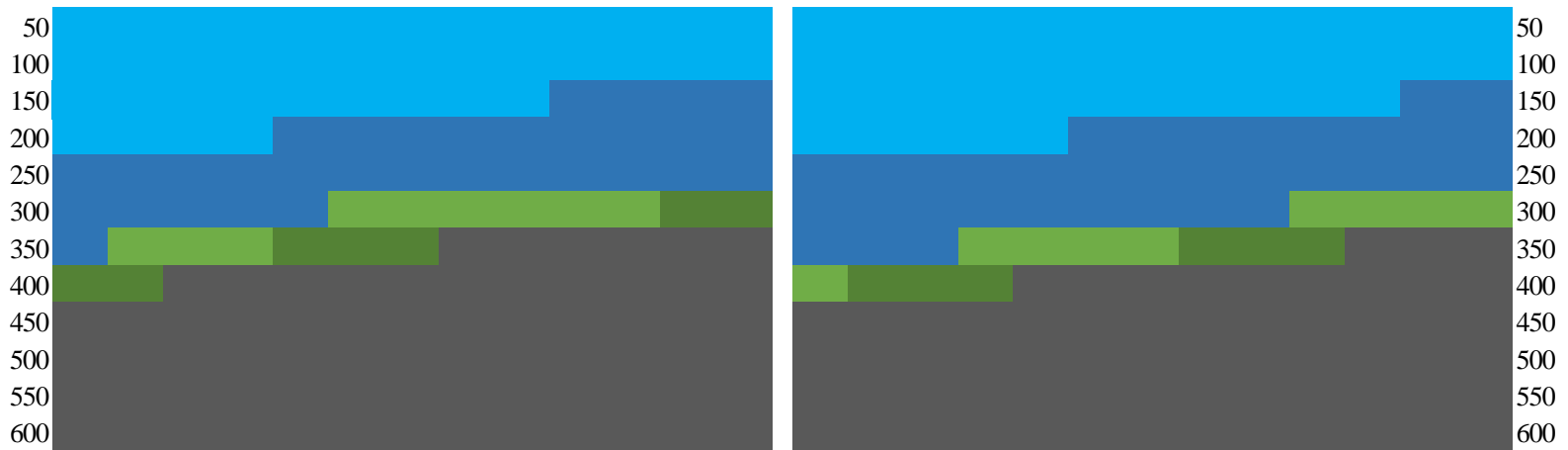


# INTERSECTION 1, LOS TURNING VEHICLES



a) BC average delay time for turning vehicles

b) PP average delay time for turning vehicles



c) CP average delay time for turning vehicles

d) CPT average delay time for turning vehicles

LOS Definition      A    < 10    B    10 - 20    C    20 - 35    D    35 - 55    E    55 - 80    F    > 80



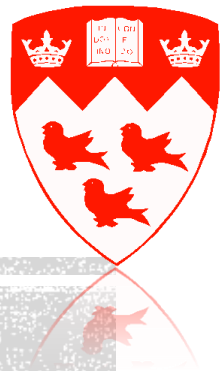
# CONCLUSIONS

- The effectiveness of the CP design is clear, with the lowest number of crossing conflicts between vehicles and cyclists.
- The second safest scenario is the PP, followed by the CPT and BC, the most dangerous of the four cases.
- Although the CP is the phase with the lower number of conflicts, it is also the phase with longest and most variable delay.
- From these results, the PP signal design is able to improve cyclist safety without greatly affecting LOS for vehicles and cyclists.



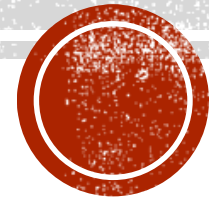


**McGill University  
Civil Engineering & Applied Mechanics**



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**Thank you for your attention**



**CONACYT**

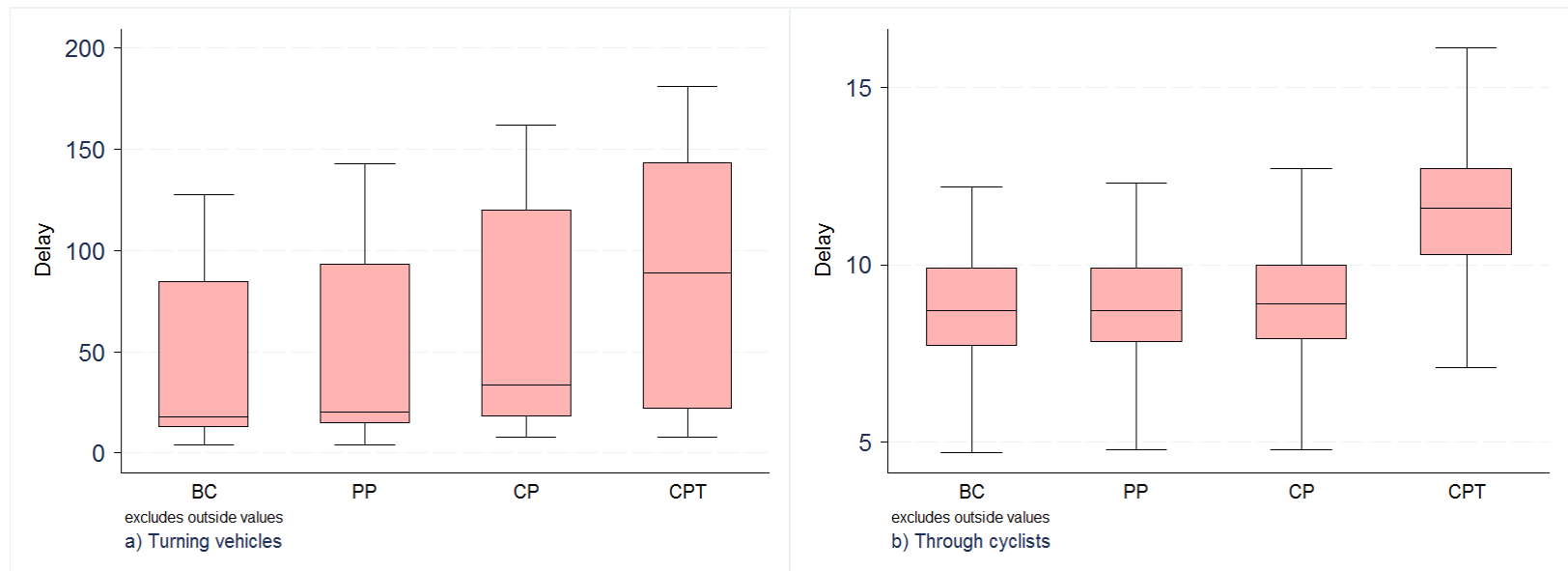


**McGill**

June , 2017. Toronto, Ontario

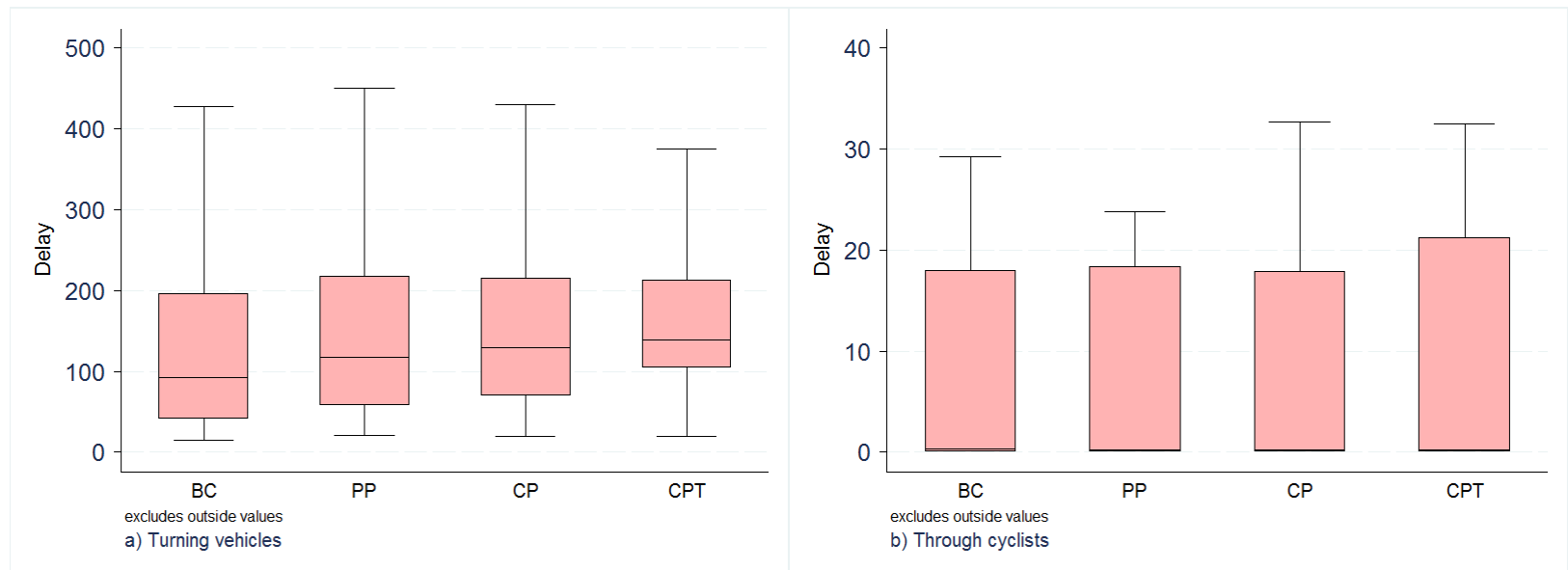
# RESULTS, INTERSECTION 2 SUMMARY

Variable	Light phase			
	BC	PP	CP	CPT
Through vehicles median (s)	18.6	19.9	35.1	90.3
Through vehicles IQR (s)	73	80.8	101.2	120.9
Turning vehicles median (s)	18	20.35	33.7	88.95
Turning vehicles IQR (s)	71.8	78.5	101.9	121.4
Through cyclists median (s)	8.7	8.7	8.9	11.6
Through cyclists IQR (s)	2.2	2.1	2.1	2.45
Crossing conflicts	416	330	182	247



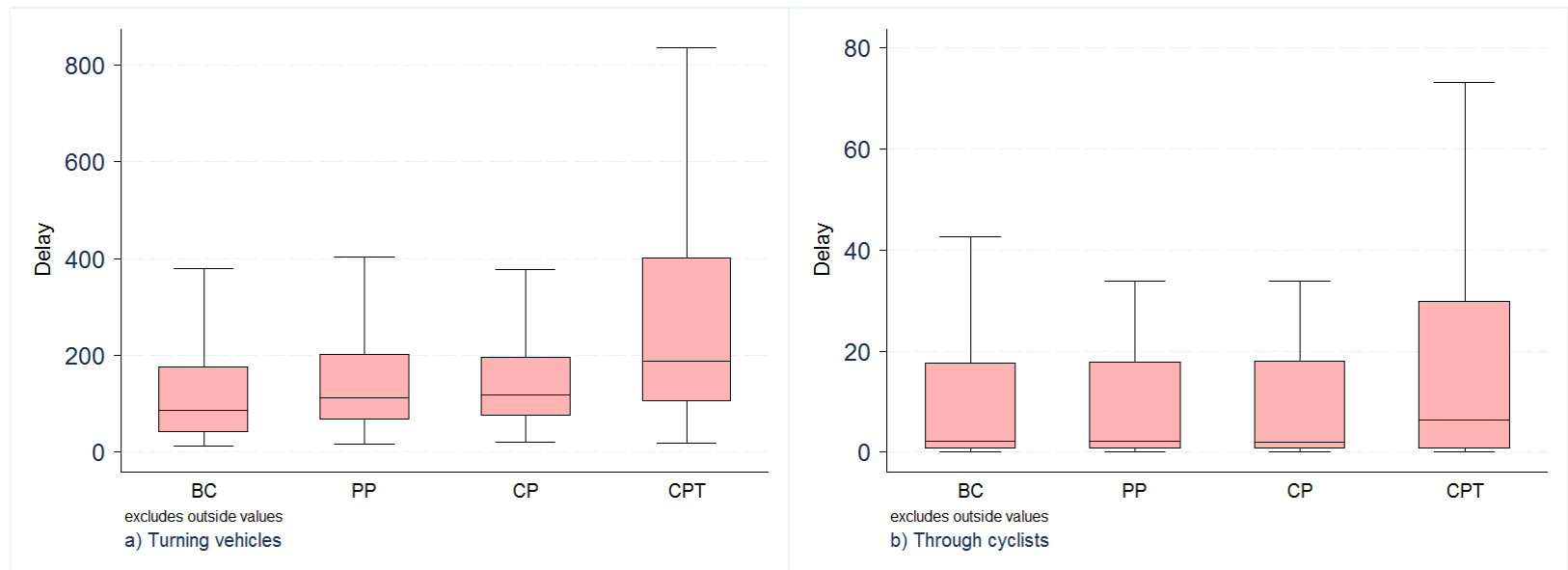
# RESULTS, INTERSECTION 3 SUMMARY

Variable (%)	Light phase, turning direction			
	BC	PP	CP	CPT
Through vehicles median	10.6	10.8	16.7	20.0
Through vehicles IQR	3.6	4.8	8.45	9.75
Turning vehicles median	17.5	20.6	23.6	23.9
Turning vehicles IQR	22.35	30.5	66.95	41.95
Through cyclists median	8.4	8.3	8.3	10.8
Through cyclists IQR	1.9	1.8	1.9	2.4
Crossing conflicts	4051	2681	2642	2894

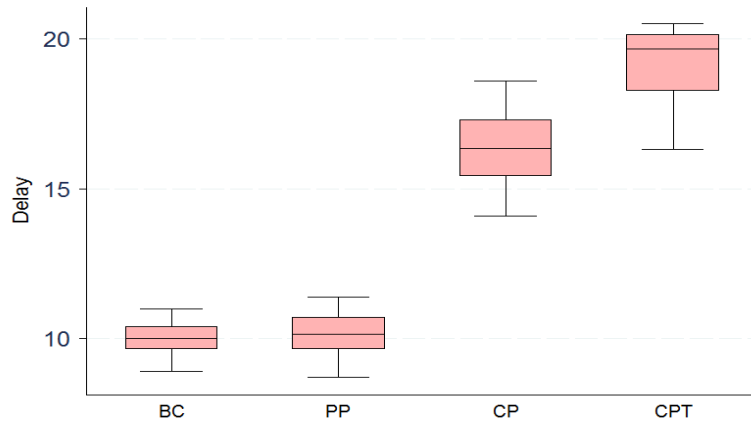


# RESULTS, INTERSECTION 4 SUMMARY

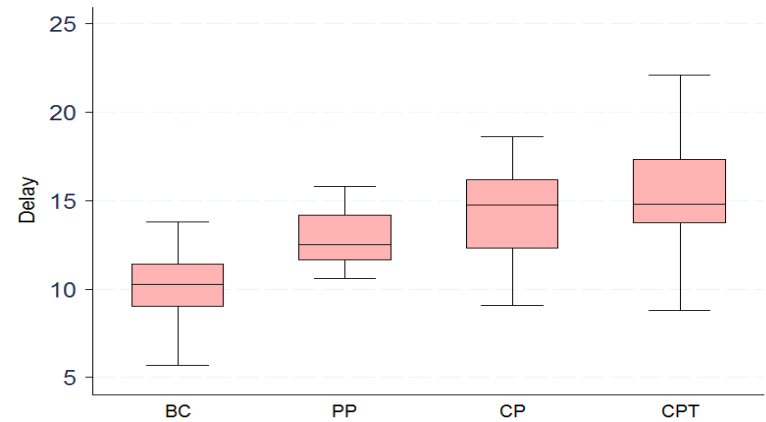
Variable (%)	Light phase, turning direction			
	BC	PP	CP	CPT
Through vehicles median	10.6	10.8	16.7	20.0
Through vehicles IQR	3.6	4.8	8.45	9.75
Turning vehicles median	17.5	20.6	23.6	23.9
Turning vehicles IQR	22.35	30.5	66.95	41.95
Through cyclists median	8.4	8.3	8.3	10.8
Through cyclists IQR	1.9	1.8	1.9	2.4
Crossing conflicts	38	16	29	23



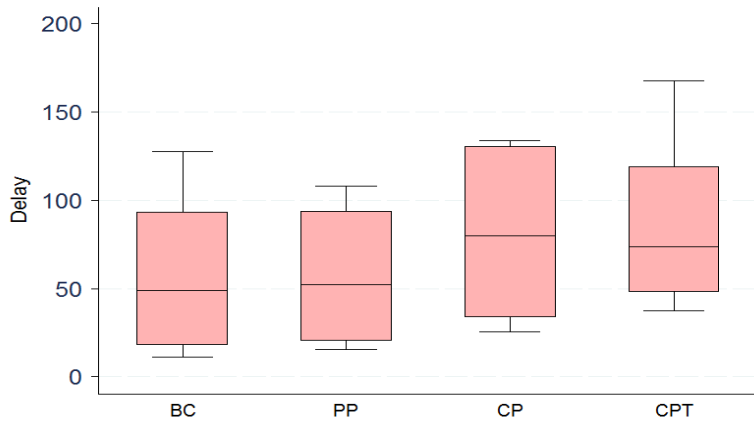
# VEHICLES DELAY



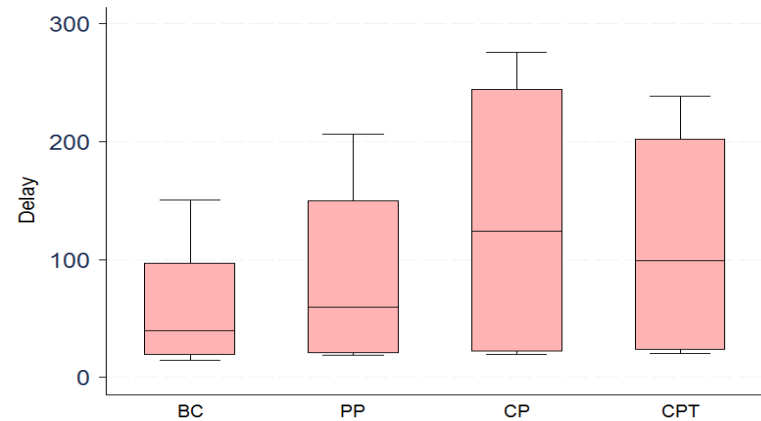
excludes outside values  
a) Through vehicles, 300 vehicles - 150 cyclists per hour



excludes outside values  
b) Turning vehicles, 100 vehicles - 50 cyclists per hour



excludes outside values  
c) Through vehicles, 600 vehicles - 500 cyclists per hour



excludes outside values  
d) Turning vehicles, 400 vehicles - 350 cyclists per hour

