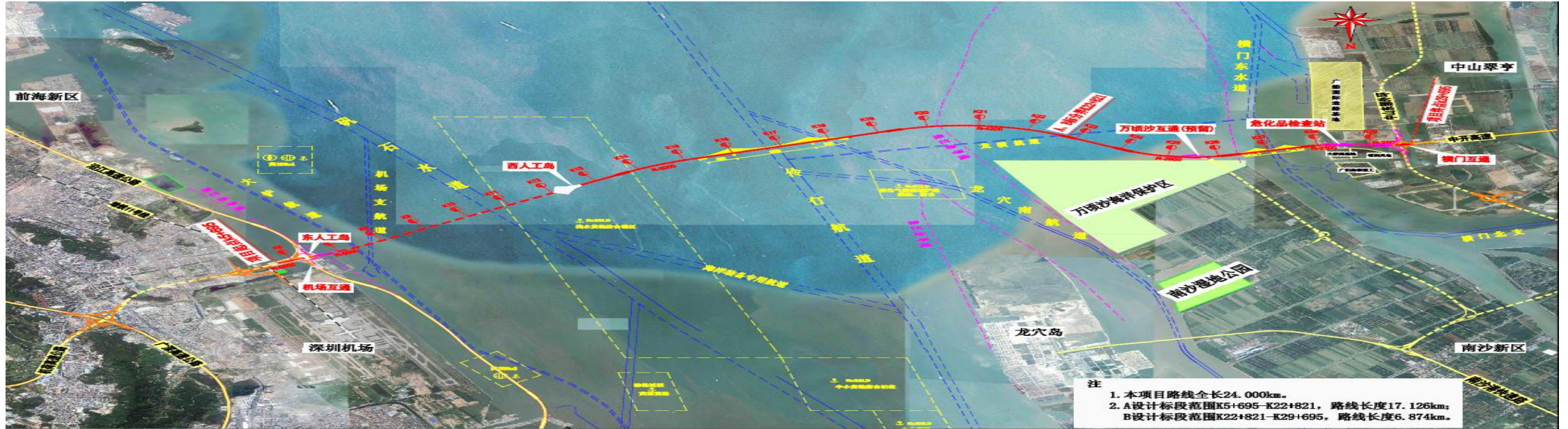


Study on Framework of Traffic Operational Safety Assurance Program and Real-time Crash Risk Prediction Model of Shenzhen-Zhongshan Corridor



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Outline

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4.2 Establishing the Real-Time Crash Risk Prediction Model

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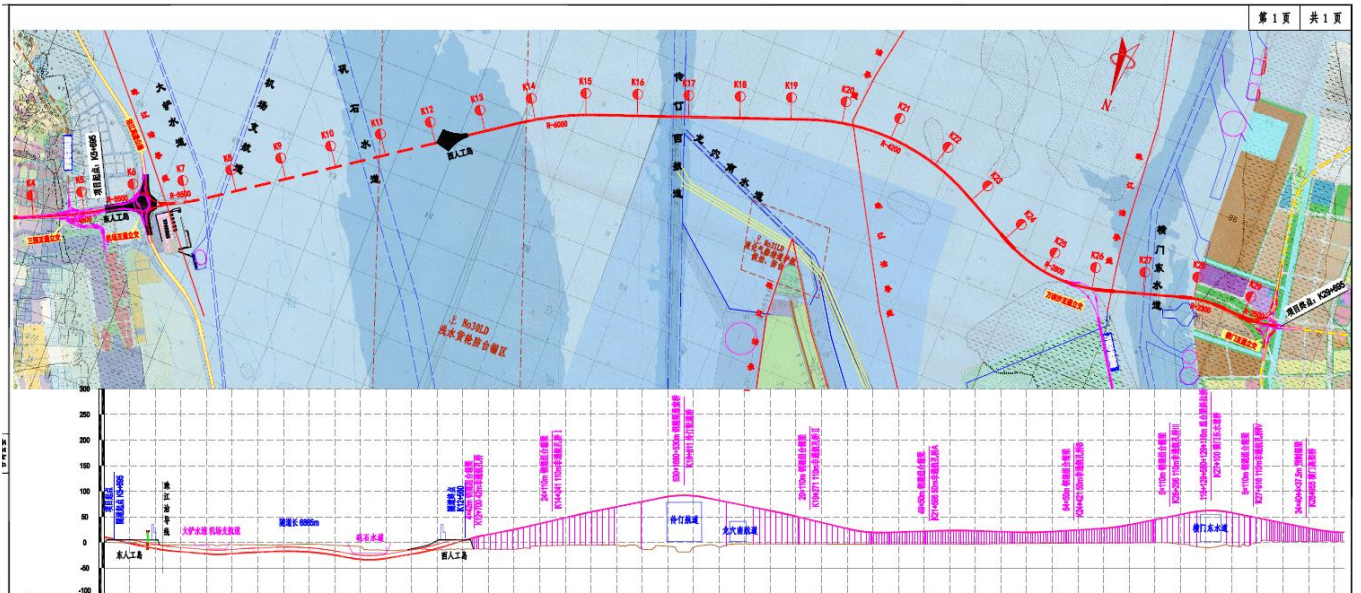
1. Background of the “Mega” corridor

A 24-km long corridor across the sea outfall of Pearl River, Guangdong Province (close to Hong Kong), combined with 2 man-made islands, a tunnel, and a bridge

Directly connecting two major cities: Shenzhen (pop: 11.4 m) and Zhongshan (pop: 3.1 m)

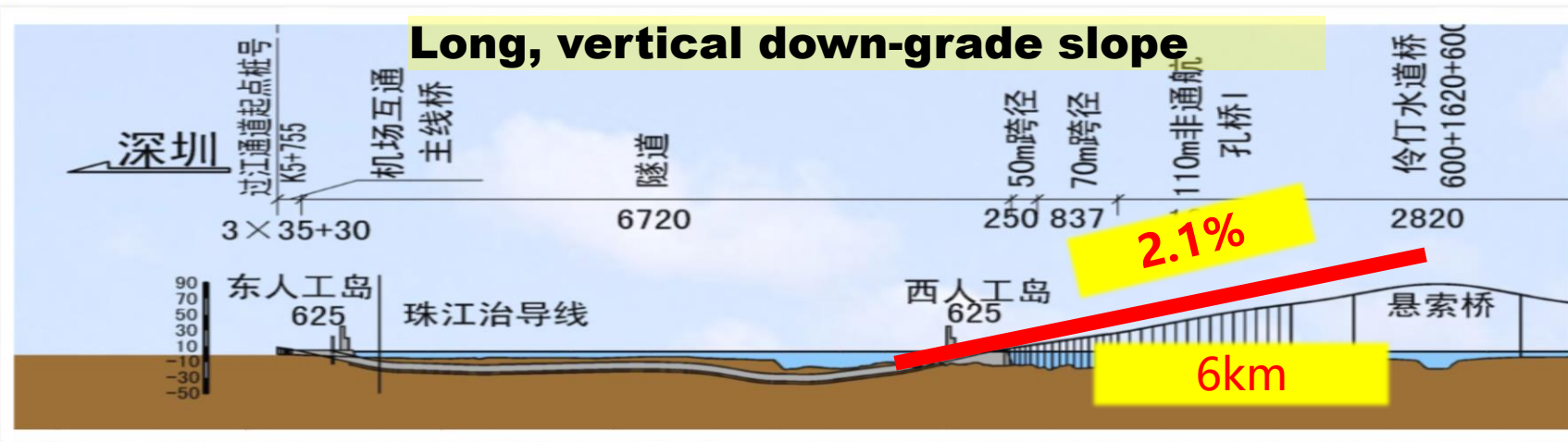
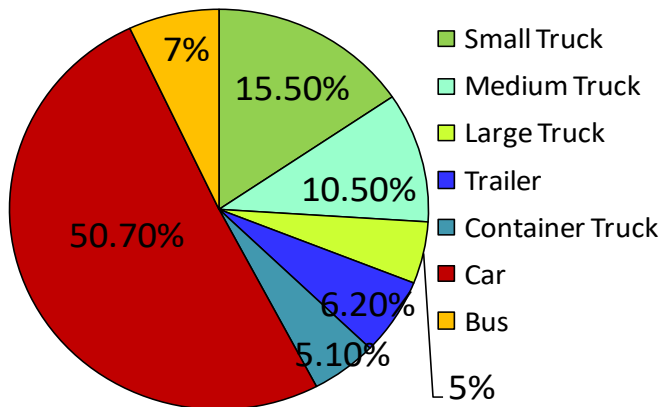
- Current stage: detail design
- Construction time period: 2017-2024

- Tunnel section: 6865 m
- Bridge section: 17054 m
- 8-lane roadway
- Design speed = 100km/h
- Horizontal min R = 2300m
- Vertical min R = 16000m
- Max slope = 2.98%



2. Major Road Safety Concerns

•> 90k pcu/d
 •≈50% trucks
 •high % of dangerous goods and over-sized vehicles



R&D on an operational safety assurance program

Transition Page



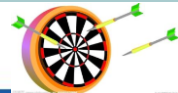
Part 3

Framework of Traffic Operational Safety Assurance Program

Project: Traffic Operational Safety Assurance and Emergent Response of Shen-Zhong Corridor

Main Goal: mitigate operational safety concerns

Sub-project 1: Management of dangerous goods freight	Sub-project 2: Ventilation and fire control system	Sub-project 3: Traffic operational management, control and safety	Sub-project 4: Emergent response and rescue
Target: Dangerous Goods	Target: Ventilation & Fire	Target: Safety & Control	Target: Response & Rescue

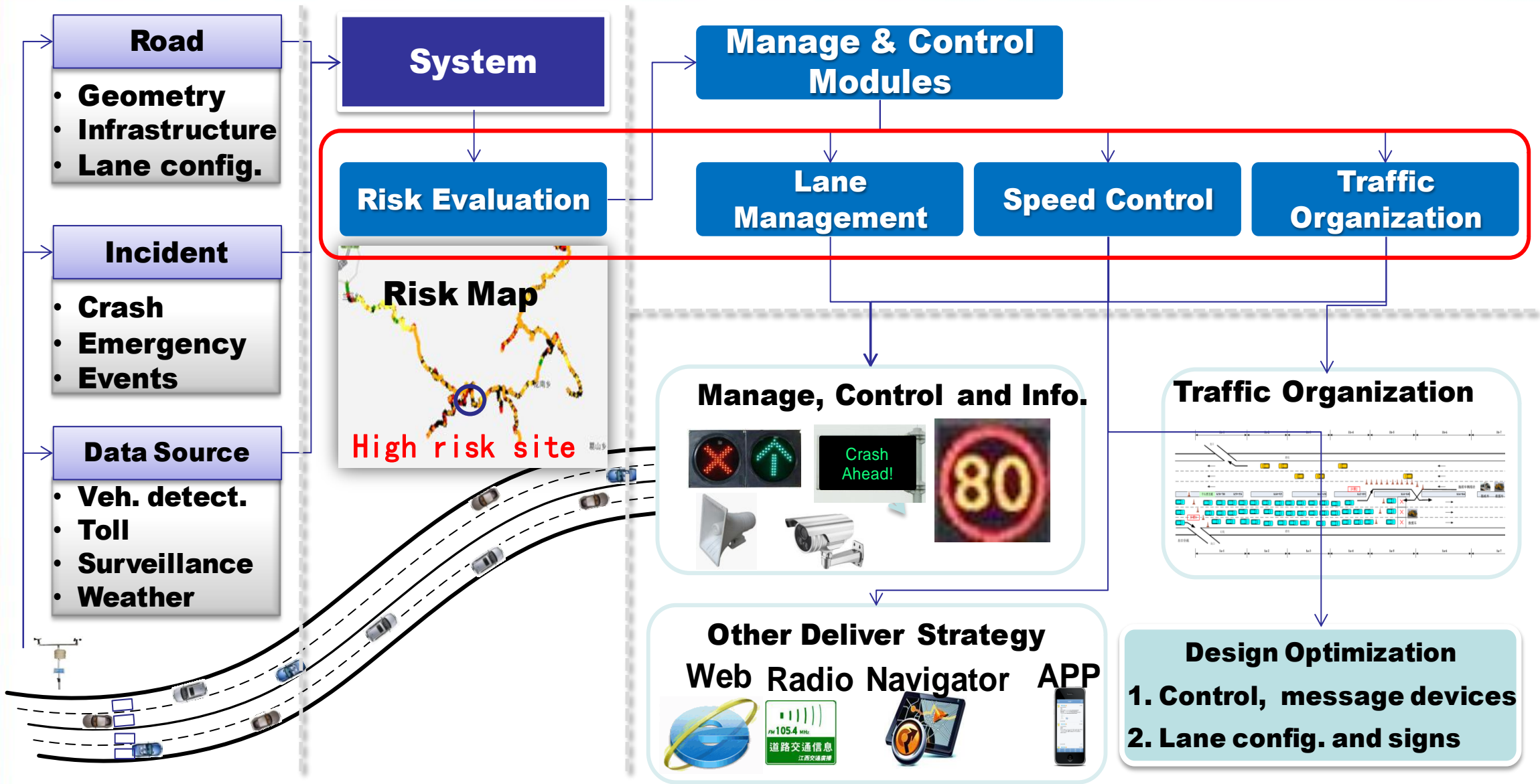


3.2 The Safety Program to Be Developed

Sub-project 3: Traffic operational management, control and safety

Topic 1: Road safety evaluation by simulation with the driving simulator	Topic 2: Advanced illumination and safety	Topic 3: Intelligent traffic operational management and control	Topic 4: Traffic signs and guidance system inside underground interchange	Topic 5: Solutions against severe weather	Topic 6: R & D on an advanced video and sound incident detection system	Topic 7: The traffic operational safety manual
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**A safety assurance program
with ATM measures**



Real-time Crash Risk Prediction Model

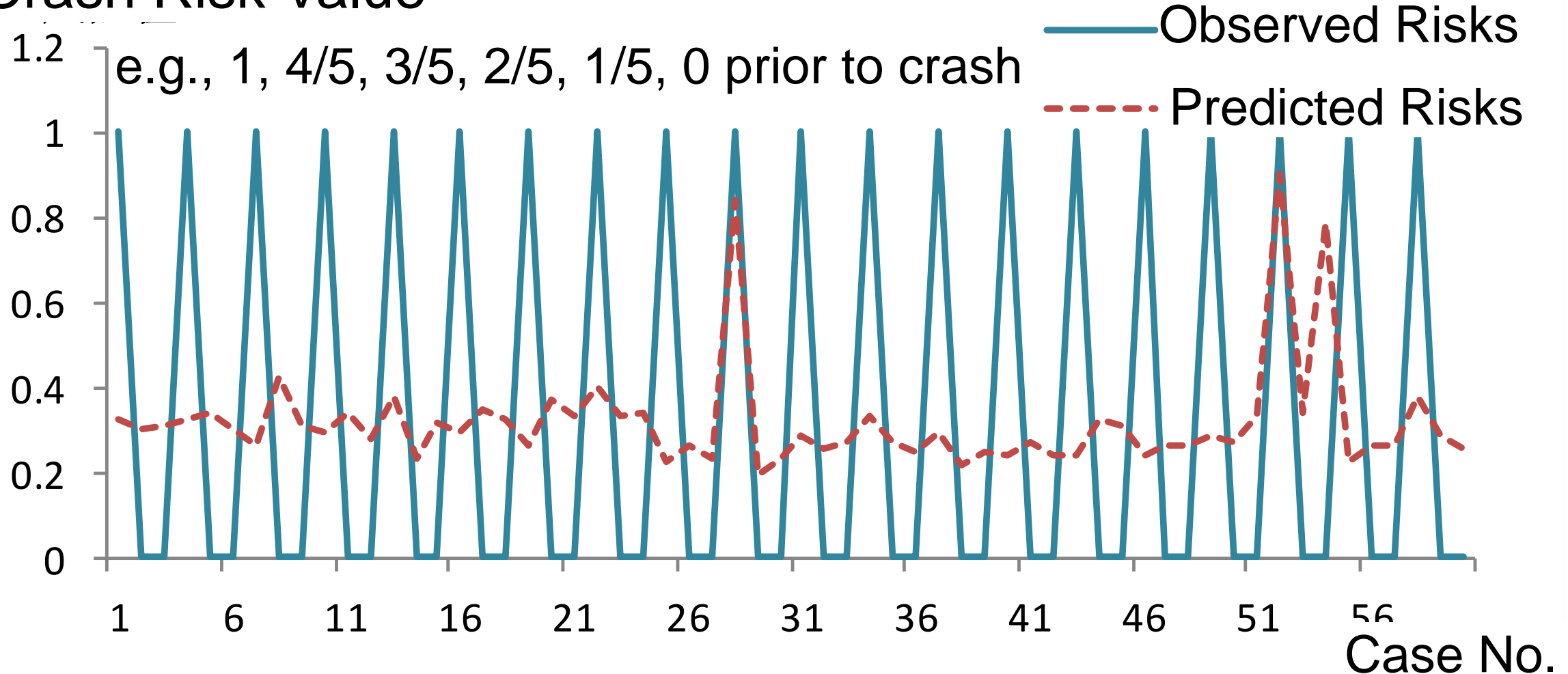


2-step mechanism: step 1 - identify major contributors to risk, step 2 - input major contributors into model to predict risks.

4.1 Defining Risk & Identifying Main Factors

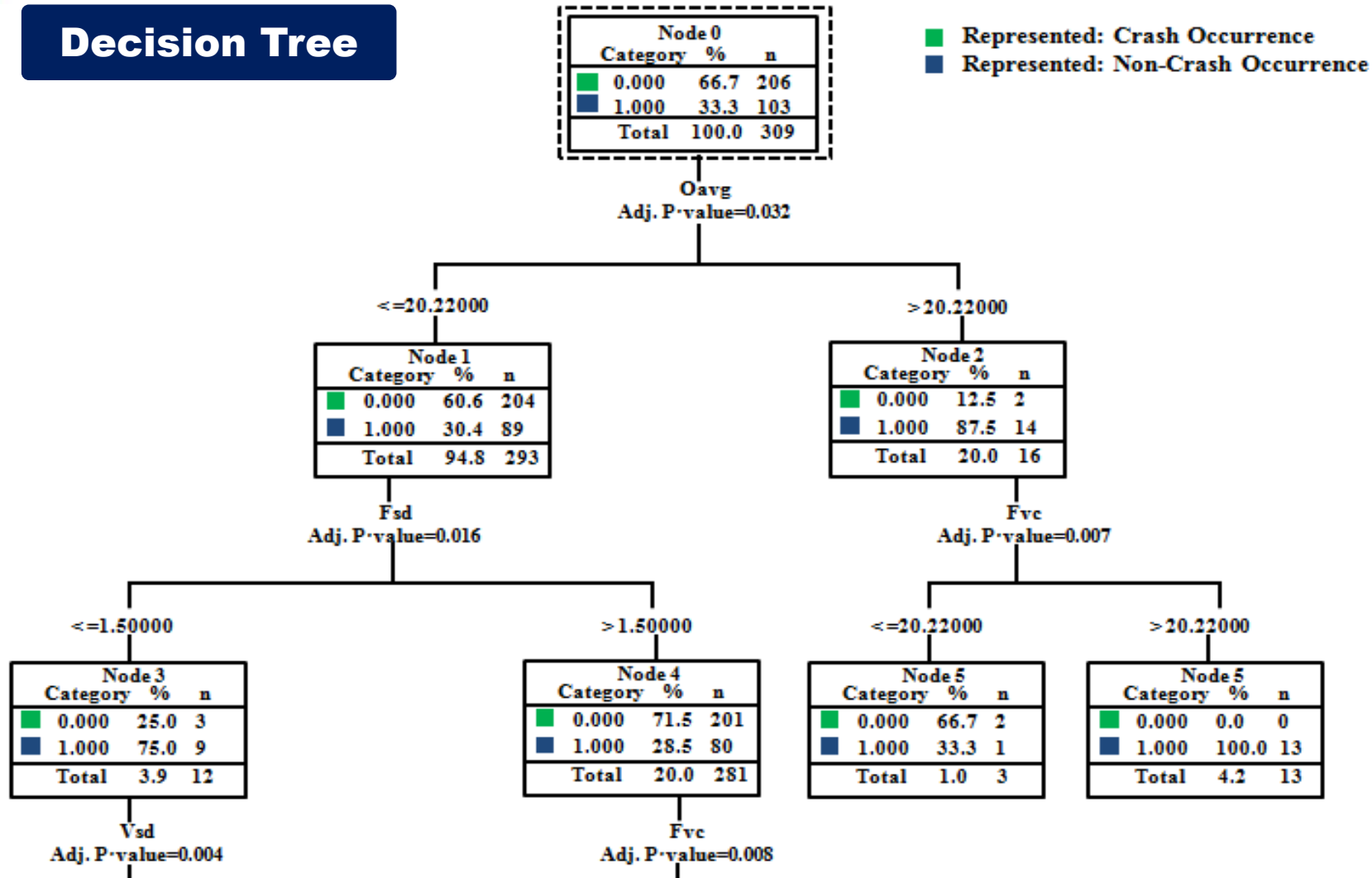
Crash Risk Value

e.g., 1, 4/5, 3/5, 2/5, 1/5, 0 prior to crash



4.1 Defining Risk & Identifying Main Factors

Decision Tree

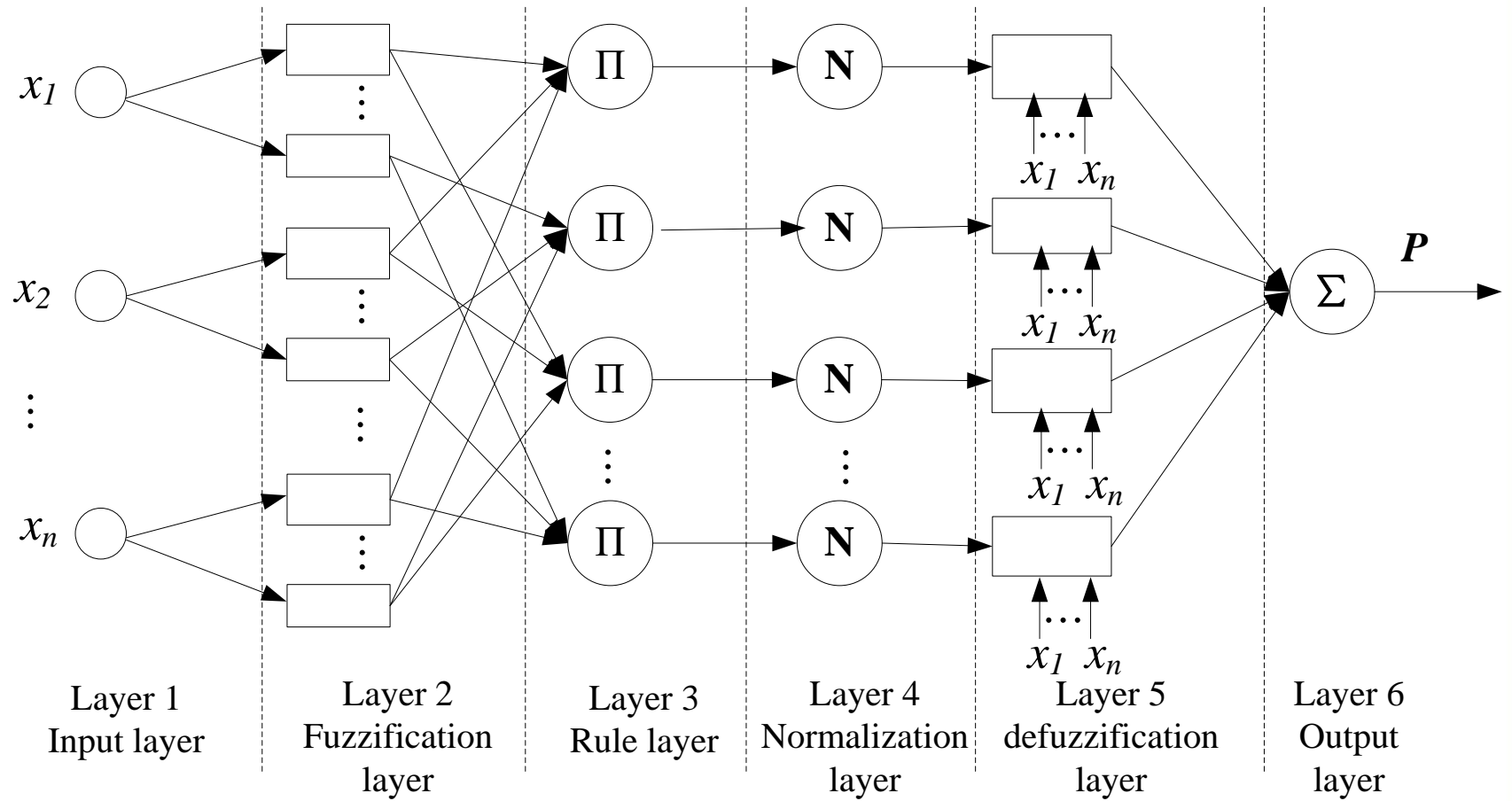


Main Traffic Flow Factors Identified

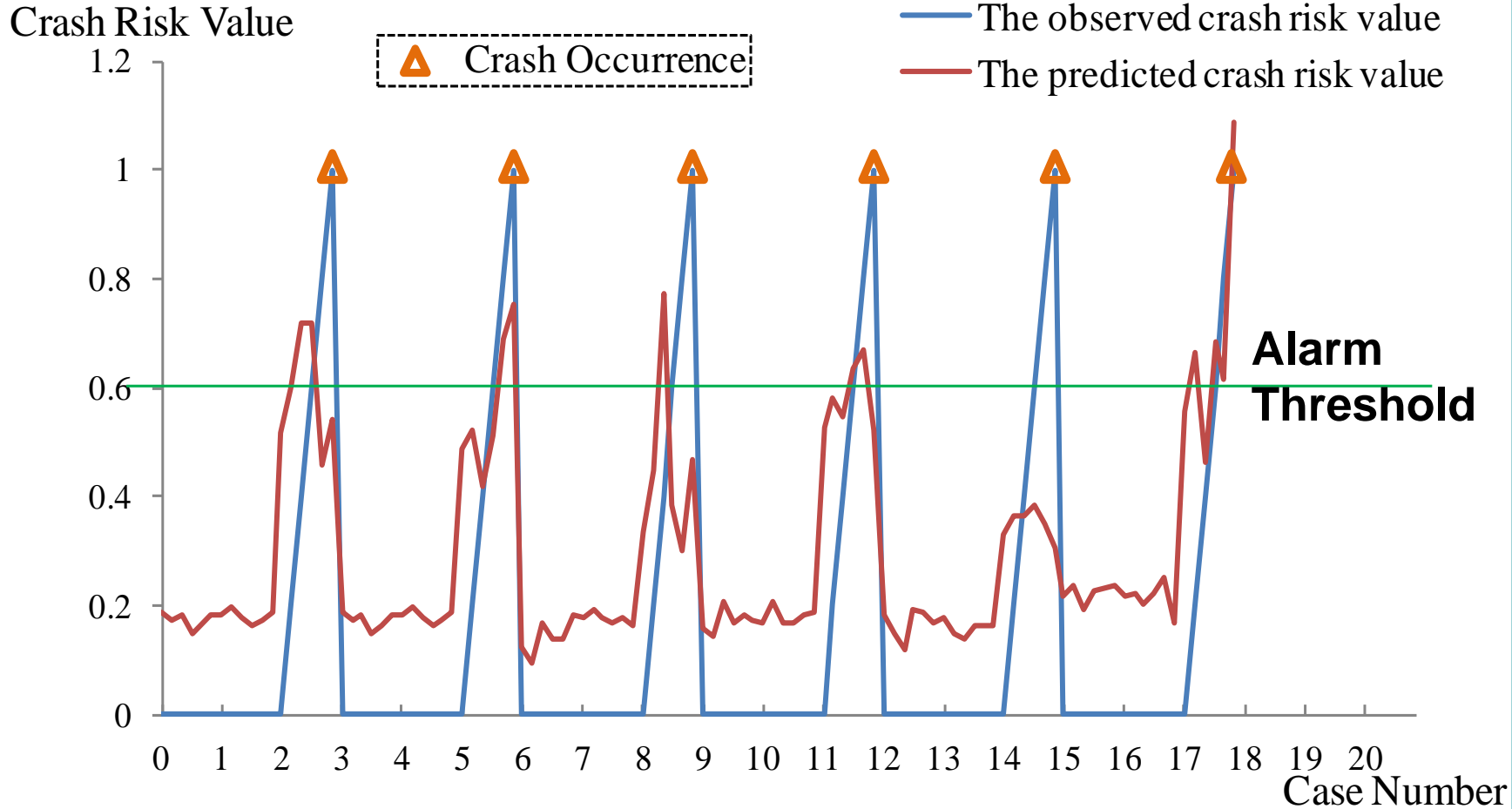
$O_{avg} \rightarrow$
 $F_{sd} \rightarrow$
 $F_{vc} \rightarrow$
 $V_{avg} \rightarrow$
 V_{sd}

4.2 Establishing the Real-Time Crash Risk Prediction Model

Structure of Adaptive Neuro-Fuzzy Inference System (ANFIS)



4.3 Model Results



**13 out of 20
crashes were
correctly
alarmed
(accuracy
rate=65.0%)**

**3 of 40 non-
crash cases
were predicted
as “crash”(false
alarm rate=7.5%)**

5. Discussion and Conclusions

- safety concerns were accurately captured
- The safety assurance program was accepted by the designer
 - changeable lane configuration signs
 - variable posted speed limit signs
 - facility provisions to fulfill incident traffic organization
- Alarm accuracy rate (65%) and false alarm rate (7.5%) are acceptable for engineering practices
- Further indications for next step mitigations



5. Discussion and Conclusions (continued)

- Both alarm accuracy and false alarm rates can be further improved
- To be trained and calibrated by real Shen-Zhong Corridor traffic data during its operation
- Develop a user-friendly software to run risk model



R&D on Program of Real-time Crash Risk Prediction

R&D of Real-time crash risk prediction and visualization program based on open source tools MySQL、Python、Baidu Map (under construction)



THANK YOU!



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RESEARCH INSTITUTE OF HIGHWAY MINISTRY OF TRANSPORT



FIRESEEDS NORTH
INFRASTRUCTURE

