











#### POLYTECHNIQUE Montréal

WORLD-CLASS ENGINEERING

#### Levels of Automation

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### Science Fiction?

Let's see how well the Active Lane Control works on the new Infiniti Q50S



### Science Fiction?

# Volvo develops the 'no death' car: Vehicles which drive themselves and are totally crashproof could be on British roads in eight years

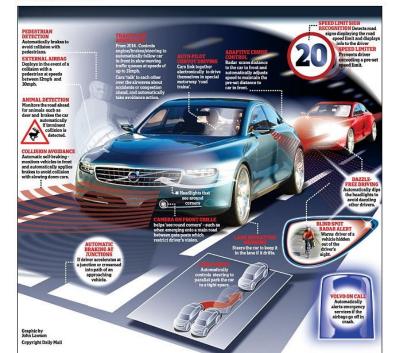
- Vehicle will be fitted with sensors that can detect potential collisions and take action
- . Firm claims 'nobody will be killed or injured in a new Volvo by 2020'

Car giant Volvo is developing 'no death' cars that drive themselves and are impossible to crash – ready for launch in showrooms within eight years.

The computerised vehicles will be fitted with high-tech sensors and will 'refuse to be steered' into other objects.

Volvo says they will be on sale to customers by 2020, but that some of the life-saving technology will be incorporated into its vehicles even earlier – from 2014 – it says.

#### Scroll down for video



# Science Fiction?



# Connected Vehicles?



## Levels of Automation

| SAE<br>level                                  | Name                      | Narrative Definition   | Execution of<br>Steering and<br>Acceleration/<br>Deceleration | Monitoring<br>of Driving<br>Environment | Fallback<br>Performance<br>of <i>Dynamic</i><br><i>Driving Task</i> | System<br>Capability<br>(Driving<br>Modes) |
|---|---------------------------|--|---|---|---|--|
| Human driver monitors the driving environment |                           |  |   |   |   |  |
| 0   | No<br>Automation          | the full-time performance by the <i>human driver</i> of all aspects of the <i>dynamic driving task</i> , even when enhanced by warning or intervention systems   | Human driver  | Human driver                            | Human driver  | n/a  |
| 1   | Driver<br>Assistance      | the <i>driving mode</i> -specific execution by a driver assistance system of either steering or acceleration/deceleration using information about the driving environment and with the expectation that the <i>human driver</i> perform all remaining aspects of the <i>dynamic driving task</i> | Human driver<br>and system                                    | Human driver                            | Human driver  | Some driving<br>modes                      |
| 2   | Partial<br>Automation     | Intelligent Cruise<br>Control<br>+Active Lane Control  | System  | Human driver                            | Human driver  | Some driving<br>modes                      |
| Auton   | nated driving s           | ystem ("system") monitors the driving environment  |   |   |   |  |
| 3   | Conditional<br>Automation | Tesla  | System  | System                                  | Human driver  | Some driving<br>modes                      |
| 4   | High<br>Automation        | the <i>driving mode</i> -specific performance by an automated driving system of all aspects of the <i>dynamic driving task</i> , even if a <i>human driver</i> does not respond appropriately to a <i>request to intervene</i>   | System  | System                                  | System  | Some driving<br>modes                      |
| 5   | Full<br>Automation        | Waymo?   | System  | System                                  | System  | All driving<br>modes                       |

# Some Challenges

- Weather / Winter
- Road construction
- Legal framework
- Insurance
- Interactions with other users

# Some Impacts

- 1. Safety
- 2. Road capacity
- 3. Increase of vehicle miles traveled
  - mobility for people who cannot drive
- 4. Urban planning: parking, urban sprawl
- 5. Car ownership: shared robo-taxis, aka Uber 2.0?
- 6. Jobs, jobs, jobs

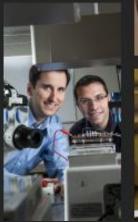
#### Conclusion

- Remember the current alternative...
  - every year: 1.2 million dead, 50 million injured
  - history will judge us harshly if we slow down the adoption of life-saving technology for the wrong reasons
- The adoption and use of disruptive technologies are difficult (impossible?) to predict





















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WORLD-CLASS ENGINEERING THANK YOU!